#### **Computational Fabrication**

CS 491 and 591 Professor: Leah Buechley https://handandmachine.cs.unm.edu/classes/Computational\_Fabrication

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https://morphingmatter.org/









Calendar check in: Data Physicalization Assignment GCODE Assignment Final Project Proposal Assignment Hand and Machine Turtle Library for Generating GCODE



# Extruder Turtle Library



Turtle generates a 3D printed path as it moves by generating g-code

https://handandmachine.org/projects/extruder\_turtle\_rhino/

# Functionality: Movement

- **t.forward**(distance) moves the turtle forward by a given distance, extruding along the way if the pen is down.
- **t.left**(theta) turns the turtle left by a given angle. This is an alias for t.yaw(theta).
- t.right(theta) turns the turtle right by a given angle. This is an alias for t.yaw(-theta).
- t.pitch\_up(theta) tilts the turtle "upwards" in the direction its eyes would point. Alias for t.pitch(theta).
- **t.pitch\_down**(theta) tilts the turtle "downwards". Alias for t.pitch(-theta).
- t.roll\_left(theta) rolls the turtle towards its left side. Alias for t.roll(-theta).
- t.roll\_right(theta) rolls the turtle towards its right side. Alias for t.roll(theta).
- t.lift(height) lifts the turtle up by a given height. Usually used to move from one layer of a print to the next.
- **t.penup**() lifts the pen up. No extrusion will occur until it is put down again.
- **t.pendown**() puts the pen down. Extrusion will occur at a constant rate with each movement unless the pen is lifted up.

https://handandmachine.org/projects/extruder\_turtle\_rhino/

# Functionality: Setup

- The constructor **t** = **ExtruderTurtle()** takes no arguments and creates a new turtle
- t.set\_extrude\_rate(extrude\_rate) sets the density of extrusion, or the rate at which filament is extruded, measured in millimeters of filament per millimeters of movement.
- **t.set\_speed**(speed) sets the "feedrate" or speed of the extruder.
- **t.setup()** writes the sequence of initialization commands to the g-code file (which moves the nozzle to its starting position, heats the bed and extruder, and so on). Optional arguments allow you to customize the setup process:
  - x=0 is the starting x-value
  - y=0 is the starting y-value
  - feedrate=1000 is the starting feedrate/speed
  - hotend\_temp=215 is the default hotend temperature
  - bed\_temp=60 is the default bed temperature
- **t.finish**() carries out the finalization sequence (moves the extruder upwards, cools the bed and extruder, etc).

# Functionality: GH/Rhino

- t.draw\_turtle() generates a triangular surface that shows you the position and orientation of the Turtle in 3D space
- t.get\_lines() generates a list of lines that allow you to visualize the path of the turtle in Rhino

#### GCode file structure

Header (supplied by library): home extruder heat up bed and nozzle extrude lines along edge

Main code (generated by turtle movement): move extruder to start point build shape with G1 commands E commands determine amount of filament extruded

Footer (supplied by library): return home turn off heaters and fans

# questions?

### Using the Library

Download or clone the library: <a href="https://github.com/Hand-and-Machine/extruder-turtle-Rhino">https://github.com/Hand-and-Machine/extruder-turtle-Rhino</a>

Save it with your other class material. Make a note of the location

Add the folder where you saved the file to your Rhino path. We'll go through these steps.

# Download again and/or fetch to get most recent version

#### Add folder to Rhino path

In Rhino: Go to Tools menu. Select Script—> Edit

Then, go to (new) **Tools** menu Select **Options** 

Tools	Analyze	Render	Window
Object Snap		>	
Commands		>	ac Solid
Script		>	Run
Grassho	opper		Edit

Tools	Window	Help	
Open Command Prompt 쇼 ૠ		<del>ሪ</del>	
Open File Prompt		жР	
Options			ж,

# Add folder to Rhino path C# 9 Python 3

In the Options window: Click on the **Python 3** tab

At the bottom of the window, add the **extruder\_turtle** folder to **Module Search Paths**. Note, this folder is inside the top level extruder-turtle-Rhino folder.

Click **OK** 

Show White Spaces	Default
Use Tab Indents  😲	Default
Show Indentation Guides	Default
Show Minimap	Default
Language Support Options	
Diagnostics (Linting)	Default
Autocomplete	Default
Word-based Autocomplete  😲	Default
Autocomplete in Function Help 😲	Default
Module Search Paths	<b>王</b>
/Users/Leah/Documents/GitHub/extruder-turtle-R	hino/extruder_turtle
/Users/Leah/Documents/GitHub/jaime_slicer /Users/Leah/Documents/GitHub/weaveSlicerPy	
Restore Defaults	ОК

IronPython 2

#### Quit and Restart Rhino

#### Open Grasshopper

### Open an example program

basic\_turtle\_examples Untitled.gcode examples extruder turtle > LICENSE Navigate to the April README.md 🔚 reload\_library.gh examples—>basic\_examples starting\_example.gh folder in the extruder-turtle-Rhino folder you downloaded March 🛴 turtle\_shapes.gh Open starting\_example.gh 

Check to make sure it runs and you don't get library errors. If it doesn't run, something went wrong with installation. Go through the steps again.

### starting\_example.gh

This is a simple program that demonstrates how to get started with the Extruder Turtle Library It generates a gcode file that follows the path of the turtle. More information: https://handandmachine.org/projects/extruder\_turtle\_rhino/examples.html



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```
import rhinoscriptsyntax as rs
import extruder_turtle
from extruder_turtle import *
```

```
# set up the turtle and associate the
# turtle with a specific printer
t = ExtruderTurtle()
t.setup(filename=file, printer = "ender")
```

```
# print out important printer parameters
t.print_printer_information()
```

```
# do your turtle programming here
# this code draws a square prism
for j in range (10):
    for i in range (4):
        t.forward(50) # units are in mm
        t.right(90)
    t.lift(t.get_layer_height())
```

### Code, top

```
# visualize the turtle's location
# and position
turtle = t.draw_turtle()
```

```
# visualize the printer's print bed
print_bed = t.draw_print_bed()
```

```
# get the path the turtle has
# traveled to visualize in Rhino
lines = t.get_lines()
```

```
# get the approximate print time
t.get_print_time()
```

```
# close the generated .gcode file
t.finish()
```

#### Code, bottom

#### Run and look at .gcode file

G1 F1000 \*\*\*\*\*\*\*\*\*\* End printer initialization \*\*\*\*\*\*\*\*\*\*\* Nozzle size: 0.2 : Extrude width: 0.4 ; Layer height: 0.2 : Extrude rate: 0.05 ; Speed: 1000 : Mix Factor: 0.9 G1 X50.0 Y0.0 E2.5 G1 X0.0 Y-50.0 E2.5 G1 X-50.0 Y-0.0 E2.5 G1 X-0.0 Y50.0 E2.5 ; new layer G1 Z0.2 G1 X50.0 Y0.0 E2.5 G1 X0.0 Y-50.0 E2.5 G1 X-50.0 Y-0.0 E2.5 G1 X-0.0 Y50.0 E2.5 ; new layer

Look at:

Header code Note: library uses relative coordinates

Move and extrude commands

Layers

#### Open .gcode file in Cura



#### Look at library documentation

#### **Extruder Turtle Library**

#### Reference

This page provides detailed documentation on the functions available in the Extruder Turtle Library. Jump to a section:

#### Setup

Turtle Related Functions Euclidean Geometry Functions 3D Printer and G-Code Related Functions Rhino/Grasshopper Visualization Functions Material Related Functions

Setup		
ExtruderTurtle	Constructor. Generates a turtle object.	
	Parameters: N/A	
	<b>Returns:</b> A turtle object located at the origin.	
	<pre>Example: t = ExtruderTurtle()</pre>	
setup	Sets initial parameters for the turtle. A printer must be set either through this function or the set_printer function for the printer-based functions to work. A filename must be specified via this function for g-code generation to work.	
	The library currently supports the following printers:	
	Eazao Zero, "eazao" 3D Potter Super 10, "super"	

https://handandmachine.org/projects/ extruder\_turtle\_rhino/reference.html

#### Edit your code to make polygon prisms



new inputs: sides: number of sides size: size of sides height: height of prism



#### Open G-Code file in Cura



#### Printer settings and the library code

### Open reload\_library.gh

- Navigate to the
   examples—>basic\_examples
   folder in the extruder-turtle-Rhino
   folder you downloaded
- Open reload\_library.gh

#### Open reload\_library.gh

# code required so that library reloads
# use if you want to make edits to library
# and have the changes compiled here
# must be above other import statements
import sys
import operator as op
to\_delete = list()
for module in sys.modules:
 if "extruder\_turtle" in module:
 to\_delete.append(module)
for module in to\_delete:
 sys.modules.pop(module)

# begin standard import statements
import rhinoscriptsyntax as rs
import extruder\_turtle
from extruder\_turtle import \*

deletes previous library import and reloads each time this block compiles

Note: this basic framework allows you to use external python files in GH programs

#### Look at library python files

#### Open ExtruderTurtle.py

- Navigate to the extruder\_turtle folder in the extruder-turtle-Rhino folder you downloaded
- Open **ExtruderTurtle.py** in a text editor of your choice

#### Open ExtruderTurtle.py

```
import os
import math
import copy
import rhinoscriptsyntax as rs
__location__ = os.path.dirname(__file__)
class ExtruderTurtle:
    def init (self):
        self.x = 0
        self.y = 0
        self_z = 0
        self.forward_vec = [1, 0, 0]
        self.left_vec = [0, 1, 0]
        self.up_vec = [0, 0, 1]
        self.use_degrees = True
        self.pen = True
        self.mix factor = 0.9
        # GCODE writing and history tracking
        self.write_gcode = False
        self.track_history = True
        self.prev_points = [(self.x,self.y,self.z)]
        self.line seqs = []
        self.extrusion_history = []
```

### set\_printer function

```
# set printer parameters
def set printer(self,printer):
    if (printer=="Ender" or printer=="ender" or printer=="creatlity" ):
        if(self.out file):
            self.initseq_filename = os.path.join(__location__, "data/initseqEnder.gcode")
        self.nozzle = 0.2
        self.extrude_width = 0.4
        self.layer_height = .2
        self.extrude_rate = 0.05 #mm extruded/mm
        self.speed = 1000 #mm/minute
        self.printer = "ender"
        self.resolution = .1
        self.x size = 220
        self.y size = 220
    elif (printer=="super" or printer=="3Dpotter" or printer=="3D Potter" or printer=="3d pot
        if(self.out file):
            self.initseq_filename = os.path.join(__location__, "data/initseq3DPotter.gcode")
        self.nozzle = 3.0
        self.extrude_width = 3.4 #mostly for solid bottoms
        self.layer_height = 2.2
        self.extrude_rate = 3.0 #mm extruded/mm
        self.speed = 1000 #mm/minute = 16.6 mm/second
        self.printer = "super"
```

### edit to add/represent your printer

```
# set printer parameters
def set_printer(self,printer):
    if (printer=="Ender" or printer=="ender" or printer=="creatlity" ):
        if(self.out file):
            self.initseq_filename = os.path.join(__location__, "data/initseqEnder.gcode")
        self.nozzle = 0.2
        self.extrude_width = 0.4
        self.layer_height = .2
        self.extrude_rate = 0.05 #mm extruded/mm
        self.speed = 1000 #mm/minute
        self.printer = "ender"
        self.resolution = .1
        self.x size = 220
        self.y size = 220
    elif (printer=="super" or printer=="3Dpotter" or printer=="3D Potter" or printer=="3d pot
        if(self.out file):
            self.initseq_filename = os.path.join(__location__, "data/initseq3DPotter.gcode")
        self.nozzle = 3.0
        self.extrude_width = 3.4 #mostly for solid bottoms
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        self.printer = "super"
```

### edit to add/represent your printer

```
# set printer parameters
def set printer(self,printer):
    if (printer=="Ender" or printer=="ender" or printer=="creatlity"):
                                                                          name
        if(self.out file):
            self.initseq_filename = os.path.join(__location__, "data/initseqEnder.gcode")
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        self.printer = "super"
```

# questions?

Turtle Geometry & Euclidean Geometry are friends

#### Open a new example program

- Navigate to the
   examples—>basic\_examples
   folder in the extruder-turtle-Rhino
   folder you downloaded
- Open euclidean\_geometry.gh

#### euclidean\_geometry.gh

```
for i in range (0,361):
    # euclidean geometry: circle
    x = radius * math.cos(math.radians(i))
    y = radius * math.sin(math.radians(i))
    # set the turtle's position using coordinates
    t.set_position(x,y)
    if (i>0 and i%10 == 0):
        # turtle geometry: spikes
        t.right(90)
        t.forward(5)
        t.back(5)
        t.left(90)
```



#### Look at library documentation

#### **Extruder Turtle Library**

#### Reference

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	The library currently supports the following printers:	
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https://handandmachine.org/projects/ extruder\_turtle\_rhino/reference.html

#### Large Assignment 4: GCODE

#### **Due Dates**

Assignment : End of day, Tuesday October 22 Presentation: Thursday October 24 Initial comments: End of day, Thursday October 24 Comment responses: End of day, Friday October 25



#### Option: use clay 3D printer

### Thank you!

CS 491 and 591 Professor: Leah Buechley https://handandmachine.cs.unm.edu/classes/Computational\_Fabrication